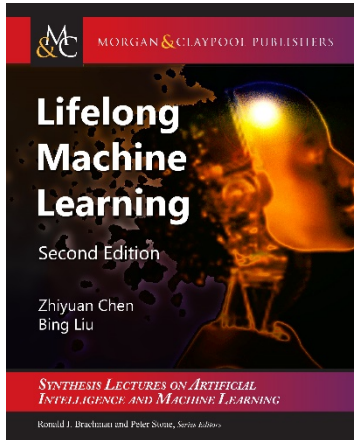

Lifelong Learning and Continuous Knowledge Learning in Chatbots



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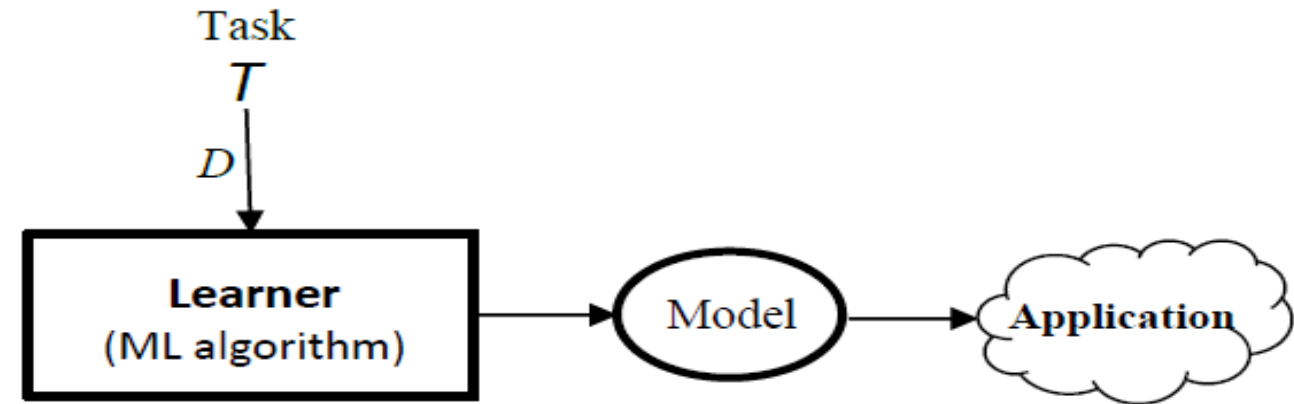
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Introduction

- Learning is key to all human and AI agent activities

- Classic machine learning

- Isolated single-task learning



- Knowledge learned not accumulated or used in new learning

- Needs a large number of training examples: cannot expect humans to label everything in the world.

- Manual labeling of data has become an industry! No education bg needed.

- Suitable for well-defined tasks in restricted and closed environment

Lifelong learning

(Chen and Liu, 2016-book)

- **Humans never learn in isolation or from scratch. We**
 - learn continuously and **accumulate knowledge** learned in the past and use it to learn more & to learn better.
 - learn in open environments in a self-supervised manner
- ***Lifelong Learning (LL)***: imitate this human learning capability
- **Goal**: Create a machine that learns like humans
 - Without it, a system will never achieve
 - **human-level intelligence** or **Artificial General Intelligence (AGI)**

Practical applications **need** LL

- **Chatbots**, personal assistants, self-driving cars, and other physical robots, working in real-life environments need LL.
 - Chatbots will not be intelligent if they cannot learn more knowledge after they are deployed
 - Impossible to know what people may say.
 - Little of our ability to converse about any subject matter is learned formally.
 - **Self-driving cars** are not going to fly with only rules and off-line training
- They face the real **open world**. No **closed-world** assumption.
 - They have to continuously learn and accumulate knowledge and adapt to new situations in a self-supervised manner.

Outline

- **What is lifelong learning?**
- Continual learning and meta-learning
- Open world learning
 - Its use in Intelligent Personal Assistant
- Learning on the job in the open world
 - Continuous knowledge learning in chatbot
- Summary

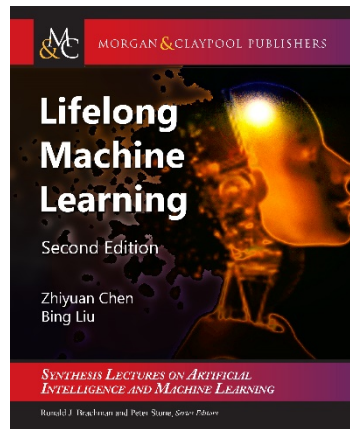
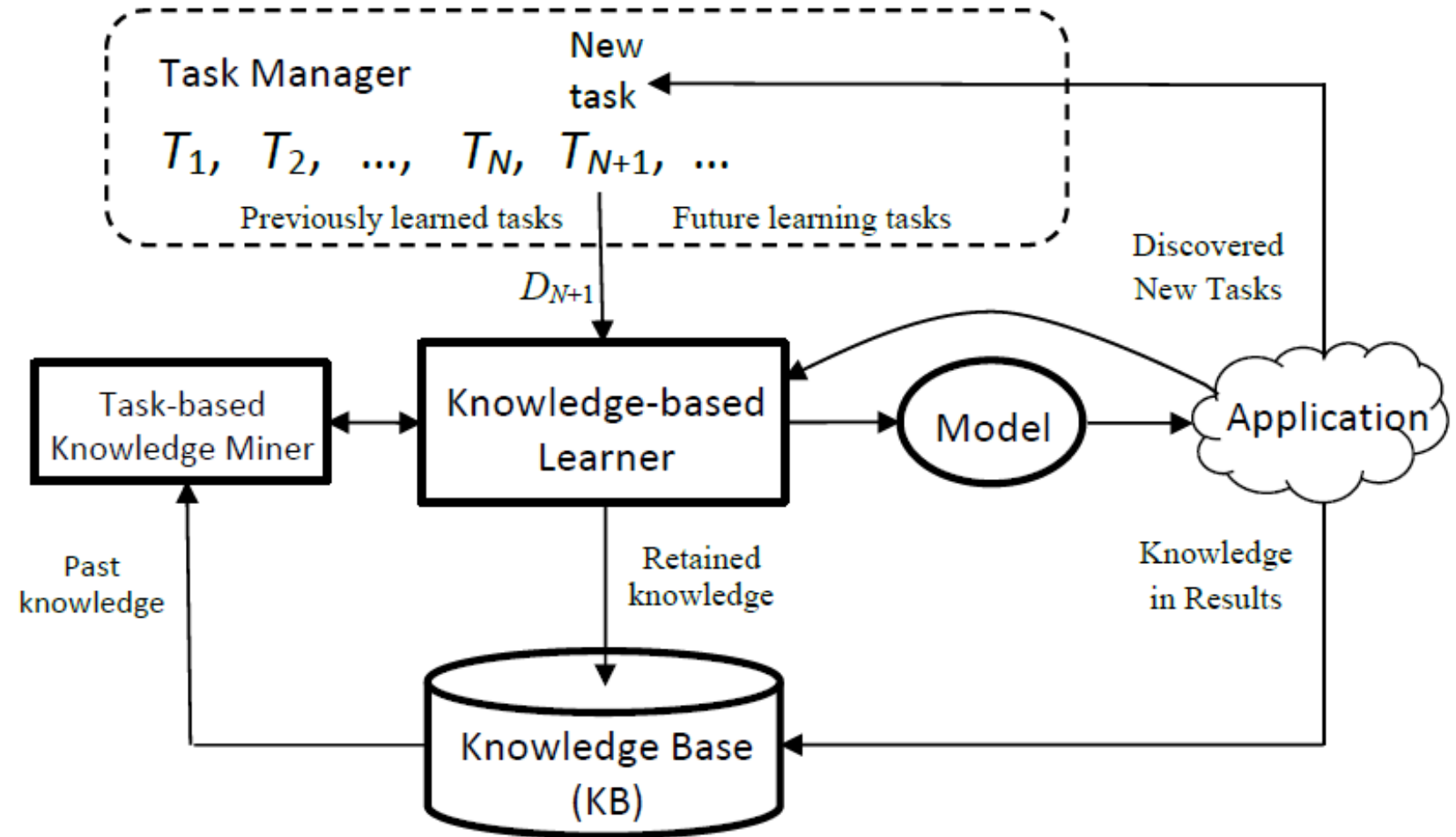
Definition of lifelong learning (LL) (existing)

(Thrun 1995, Silver et al 2013; Chen and Liu, 2016 –book)

- The learner has performed learning on a sequence of tasks, from 1 to N .
- When faced with the $(N+1)$ th task, it uses the relevant knowledge in its *knowledge base* (KB) to help learn the $(N+1)$ th task.
- After learning $(N+1)$ th task, KB is updated with learned results from $(N+1)$ th task.

Definition of lifelong learning (LL) (new)

(Thrun 1995, Silver et al 2013; Ruvolo & Eaton, 2013, Chen & Liu 2014, Fei et al 2016, Shu et al 2017a, 2017, **Chen & Liu, 2018**)



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Key characteristics of LL

(Chen and Liu, 2018-book)

1. **Continuous learning process** (w/o supervision)
 2. **Knowledge accumulation in KB** (long-term memory)
 3. **Using/adapting the past knowledge** to help future learning
 4. **Learning in the open world**, discovering new tasks & learning them incrementally in an *interactive environment* with self-motivation
 5. **Learning on the job** or learning while working, during model application or testing
- Both (4) and (5) need some form of self-supervision using agents' own knowledge and environmental feedback

Two Types of Shared Knowledge

- *Global knowledge*: These methods **assume** a *global latent structure* among tasks that are shared (Thrun, 1996, Ruvolo and Eaton, 2013, Bou Ammar et al., 2014, ...)

- Global structure \mathbf{L} : learned and leveraged in the new task learning.

$$\boldsymbol{\theta}^t = \mathbf{L}\mathbf{s}^t$$

- *Local knowledge*: **do not assume** a *global latent structure* among tasks (Chen and Liu, 2014a,b, Fei et al., 2016, Liu et al., 2016, Shu et al., 2016, 2017).
- During the new task learning, they select or meta-mine those pieces of prior knowledge to use based on need.

Approach: shared global knowledge

(Ruvolo & Eaton, 2013)

- Each model's parameter vector θ^t is a linear combination of the weight vector \mathbf{s}^t and the basis model components \mathbf{L} (Kumar et al., 2012).

$$\theta^t = \mathbf{L}\mathbf{s}^t$$

- Initial objective function

$$e_T(\mathbf{L}) = \frac{1}{T} \sum_{t=1}^T \min_{\mathbf{s}^{(t)}} \left\{ \frac{1}{n_t} \sum_{i=1}^{n_t} \mathcal{L} \left(f \left(\mathbf{x}_i^{(t)}; \mathbf{L}\mathbf{s}^{(t)} \right), y_i^{(t)} \right) + \mu \|\mathbf{s}^{(t)}\|_1 \right\} + \lambda \|\mathbf{L}\|_F^2, \quad (1)$$

Lifelong topic modeling

(Chen and Liu 2014)

- Use results from past tasks to find some topical knowledge
 - e.g., $\{price, cost\}$ & $\{price, expensive\}$
 - Use it to guide new task modeling
- Graphical model: same as LDA, but different inference
 - Generalized Pólya Urn Model (GPU)
- **Idea**: When assigning a topic t to a word w , also assign *a fraction of t* to words in must-links sharing with w .

$$P(z_i = t | \mathbf{z}^{-i}, \mathbf{w}, \alpha, \beta, \mathbf{A}') \propto \frac{n_{d,t}^{-i} + \alpha}{\sum_{t'=1}^T (n_{d,t'}^{-i} + \alpha)} \times \frac{\sum_{w'=1}^V \mathbf{A}'_{t,w',w_i} \times n_{t,w'}^{-i} + \beta}{\sum_{v=1}^V (\sum_{w'=1}^V \mathbf{A}'_{t,w',v} \times n_{t,w'}^{-i} + \beta)}$$

Open problems/challenges

- Is the past knowledge actually correct?
- Is the past knowledge actually applicable?
- What is past knowledge and how to represent it?
- ...
- LL forces us to think about the issue of knowledge and the role it plays in learning.
 - knowledge representation, acquisition, reasoning, maintenance, etc.

LL research is ramping up

- **Many related topics and names**
 - Lifelong learning
 - Never-ending learning
 - Continual learning (continuous learning)
 - Open-world learning
 - Meta-learning
 - Developmental learning (in robotics)
- DARPA program (2018): Lifelong learning machines
- DARPA program (new 2019): Open-world learning (SAIL-ON)

Transfer, Multitask → Lifelong

- **Transfer learning:** using source domain to help target domain,
 - Learning is not continuous
 - No accumulation of knowledge except data
 - Only one directional: help target domain
- **Multitask learning:** Jointly optimize multi. tasks
 - No accumulation of knowledge except data
 - Hard to re-learn all when tasks are numerous
- **Both no discovery of new problems or learning in testing**

Outline

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Continual learning and catastrophic forgetting

- **Continual learning (CL)** is mainly for solving the *catastrophic forgetting* problem in neural networks.
- **Catastrophic forgetting (CF)**: learning a new task is likely change the weights that have been learned for past tasks,
 - degrading the models for past tasks.
 - like a human brain, ideally we want a network (like a brain) to learn many tasks with little interference (or little forgetting of the past).
- **CL mainly aims to solve CF**. Unlike lifelong learning, CL usually does not emphasize leveraging the past knowledge.

Meta-learning

- **Meta-learning**, also called *learning to learn*, is often used in one-shot or few-shot learning.
- It trains a meta-model with **a large set of tasks**. Each task has a set of labeled examples.
 - The learned model can quickly adapt to a new task using only a few examples (few-shot learning).
 - Basically, meta-learning treats all these tasks as training “instances.”
- **Assume**: training tasks and test tasks - same distribution
 - But in real life, new tasks fundamentally different in some aspects.

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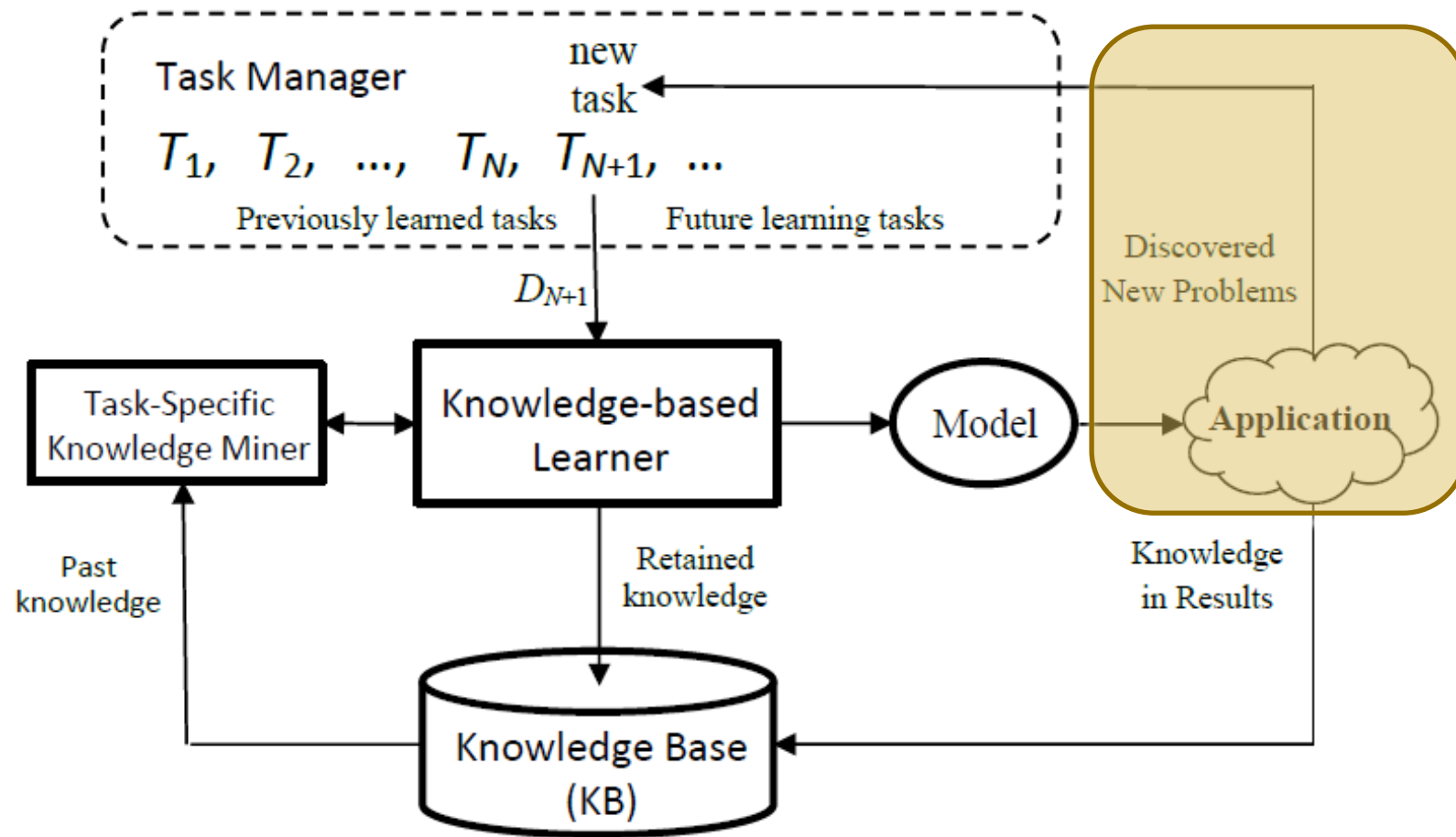
Open-world learning

(Fei et al 2016, Chen and Liu 2016, 2018)

- Traditional learning makes the **closed world assumption**:
 - What the agent sees in training is what it will see in testing.
 - **Nothing new or nothing unexpected.**
- Clearly not true **in the real-world (open) environment.**
 - Self-driving cars will see things it has never been trained for.
 - A chatbot will definitely hear something that it does not know.
- **Can the agent detect unknowns and learn them?**
 - If so, it will become more and more knowledgeable.

Open-world learning

(Fei et al., 2016; Shu et al., 2017)



Open-world Learning (OWL)

(Shu, Xu and Liu 2018)

- At any point in time, the learning system is aware of a set of seen classes $S = \{c_1, \dots, c_m\}$ and has an OWL model or classifier for S but is unaware of a set of unseen classes $U = \{c_{m+1}, \dots\}$ (any class not in S can be in U) that the model may encounter.
- **Goal:**
 - Classify seen class instances and detect unseen class instances
 - Group these instances into classes
 - Learn the new classes incrementally

Intelligent Personal Assistant needs OWL

(Xu et al, 2019)

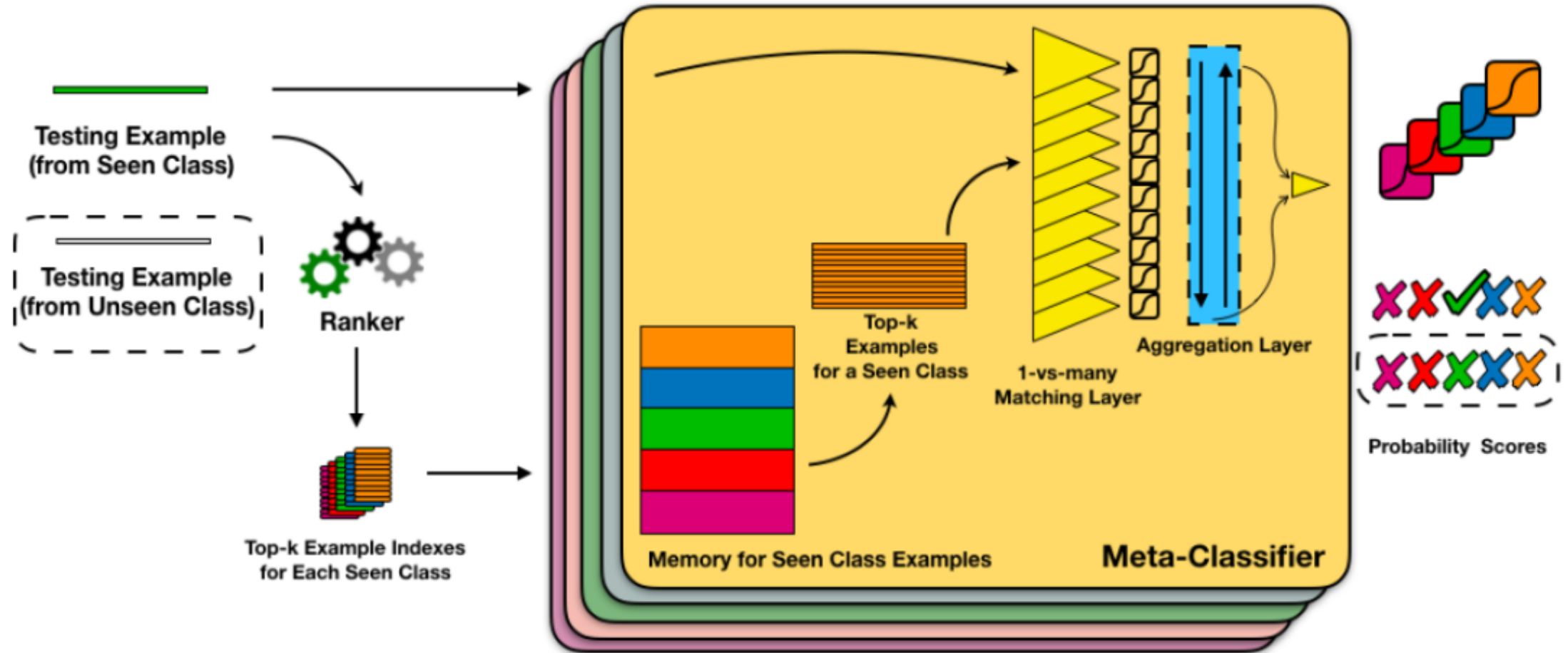
- Intelligent Personal Assistants (IPA) (e.g., Amazon Alexa, Google Assistant, and Microsoft Cortana)
 - The first task is to classify user utterances into existing known intent classes (e.g., Alexa's skills) and
 - detect utterances from unknown intent classes (not supported)
- But, with the support to allow the 3rd-party to develop new skills (Apps),
 - IPAs must recognize new/unseen intent classes and include/learn them in the classification model.

Learning to Accept Classes (L2AC)

(Xu et al, 2019)

- **Goal of L2AC is two-fold:**
 - (1) classifying examples from classes in S and reject examples from classes in U , and
 - (2) when a new class c_{m+1} (without loss of generality) is removed from U (now $U = \{c_{m+2}, \dots\}$) and added to S (now $S = \{c_1, \dots, c_m, c_{m+1}\}$), still being able to perform (1) without retraining the model.
- L2AC maintains a dynamic set S of seen classes that allows new classes to be added or deleted with no model re-training needed.

L2AC architecture



Training the meta-classifier

- Since the **meta-classifier** is a general classifier that is supposed to work for any class, training the meta-classifier

$$p_{\theta}(c|x_t, x_{a_{1:k}}|x_t, c)$$

- It requires examples from another set M of classes called meta-training classes.
- A large |M| is desirable to cover of features for seen and unseen classes in testing

DOC: Deep Open Classification

(Shu et al. 2017)

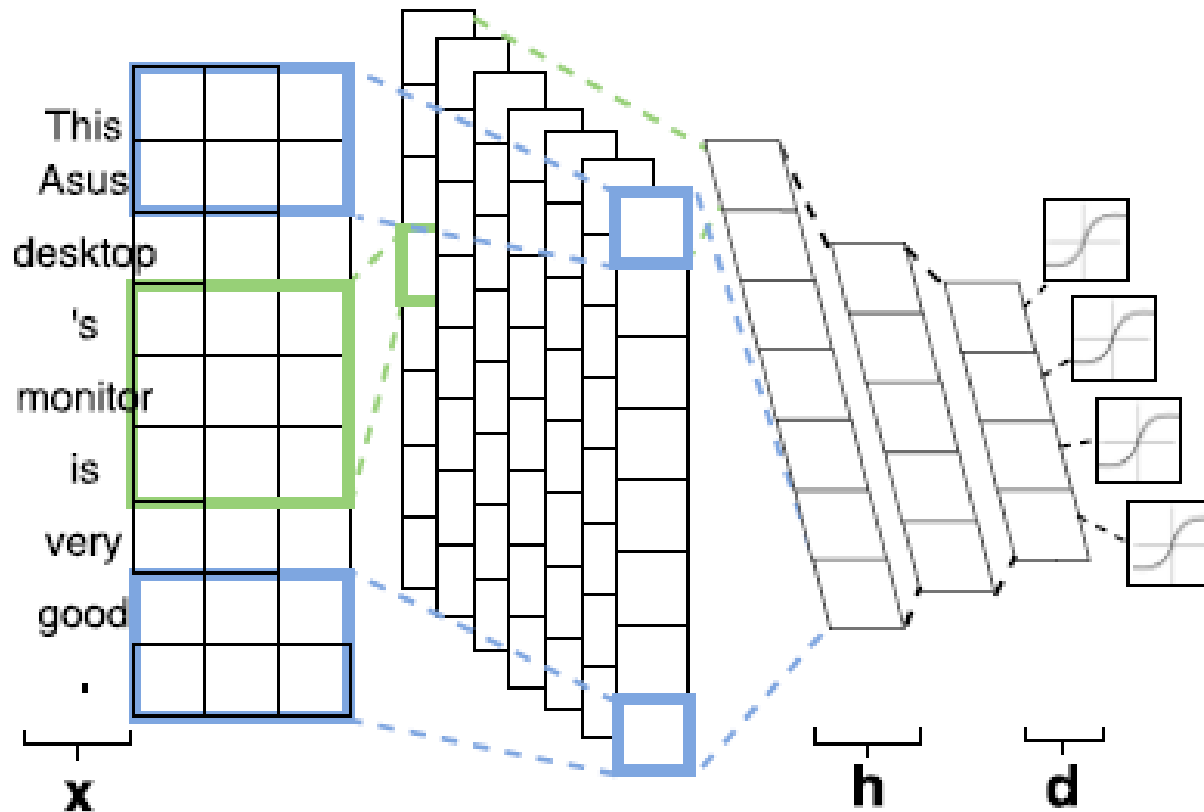


Figure 1: Overall Network of DOC

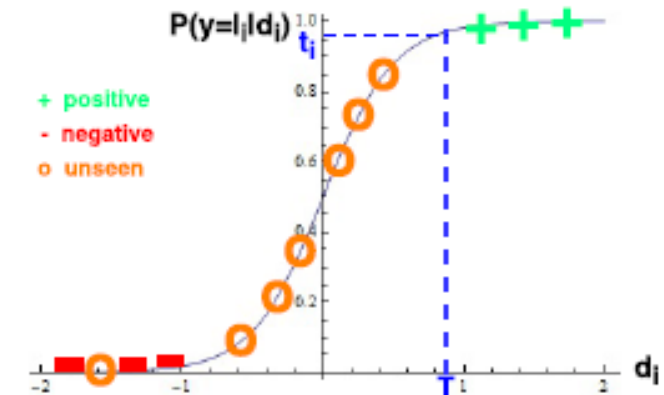


Figure 2: Open space risk of sigmoid function and desired decision boundary $d_i = T$ and probability threshold t_i .

Learning incrementally (cumulatively)

- How to discover classes (or characterize) in the unseen data?
- Incrementally add a class without retraining from scratch
- “Human learning”: uses the past knowledge F_t to help learn the new class I_{t+1} .
 - Find similar classes SC from known classes Y^t .
 - Old classes: $Y^t = \{\text{movie, cat, politics, soccer}\}$.
 - New class: $I_{t+1} = \text{basketball}$
 - SC = {soccer}
 - Building F_{t+1} by focusing on separating I_{t+1} and SC.

Outline

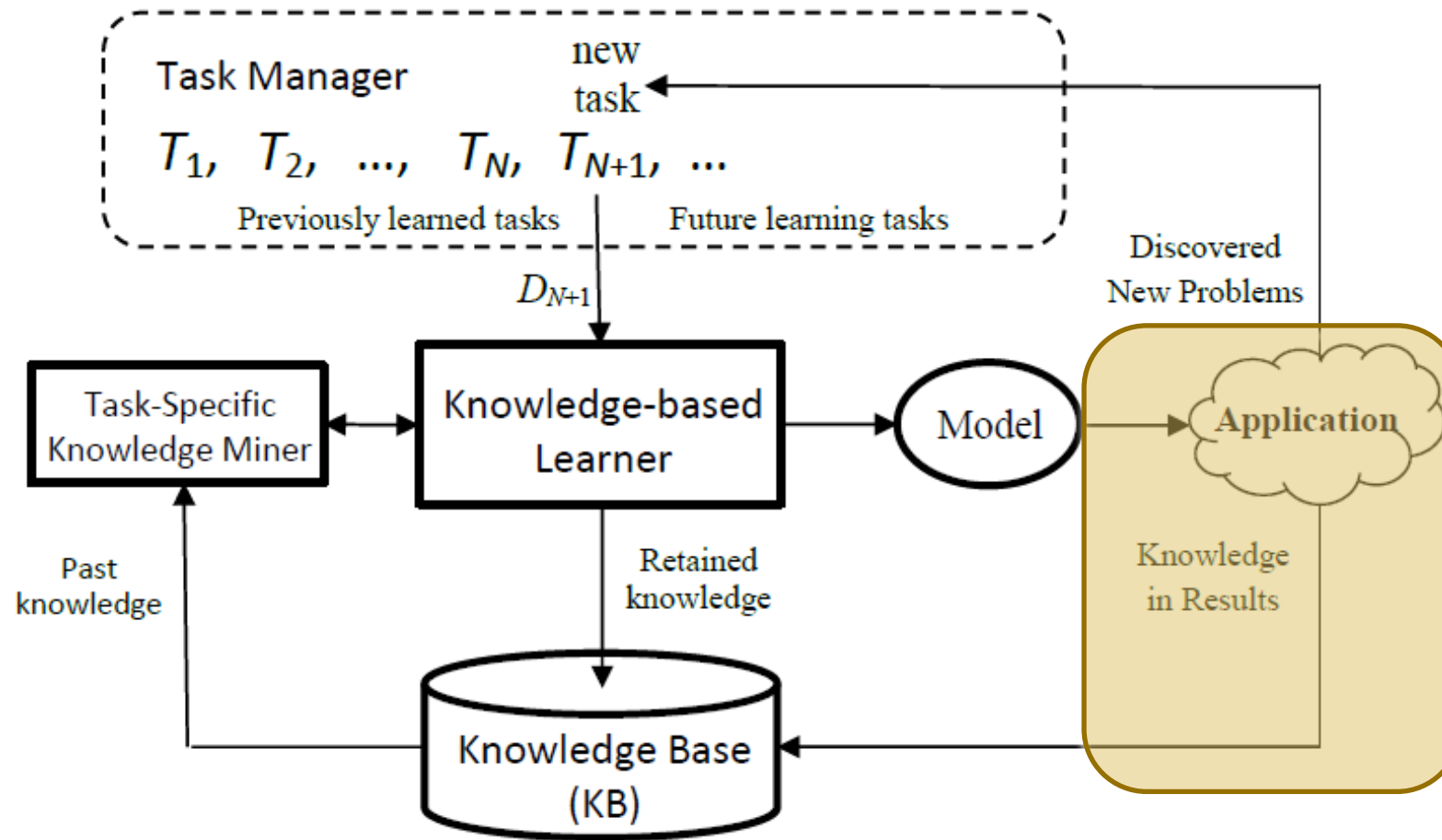
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Learning on the job (while working)

(Shu et al 2017)

- It is known in learning science that about **70% of our human knowledge comes from 'on-the-job' learning.**
 - Only about 10% through formal training
 - The rest 20% through observation of others
- **An AI agent should be able to learn on the job too** as
 - The world is constantly changing.
 - There is always new knowledge, e.g., learning during human-machine conversation (Mazumder et al., 2018)

Lifelong learning extended



Improving model in testing or application

(Shu et al 2017)

- Can a model's performance be improved after training?
- This paper proposes a technique to do so in the context of CRF for information extraction.
- **Idea:** connect features with extraction results
 - More results → better features
 - It exploits dependency features
 - As the model sees more data, more features are identified
 - The features help produce better results in the new domain using same model.

Chatbots: Learning during conversation

(Mazumder et al., 2018)

- **Chatbots:** Early chatbots were mostly built using
 - markup languages, e.g., AIML
 - handcrafted conversation generation rules, and/or
 - information retrieval techniques
- **Recently deep learning based approaches** are popular
 - They may or may not use explicit knowledge bases (KB)
 - Without using explicit KBs, produce generic/dull responses
 - Use KBs to generate knowledge grounded responses.

Major shortcoming

- One **major weakness** of existing chat systems is that
 - ❑ They do not explicitly or implicitly learn new knowledge in the conversation process.
 - ❑ This limits the scope of their applications.
- **Learning during chatting** enables chatbots to
 - ❑ learn new knowledge to expand its KB to become more and more knowledgeable.
 - ❑ improve its conversation ability.

Continuous knowledge learning engine

(Sahisnu et al., 2018)

- **lifelong interactive learning and inference (LiLi).**
- We assume relation extraction, etc, are done by other systems
- Given a query (s, r?, t) from the user, the system has the following 4 capabilities
 - 1. to formulate an inference strategy for a given query that embeds *processing* and *interactive* actions.
 - Processing action: selection of related facts, deriving inference chain, etc., that advances the inference process.
 - Interactive action: deciding what to ask, formulating a suitable question, etc., that enable interaction with the user.

Lifelong interactive learning (contd.)

- ❑ 2. to learn interaction behaviors (deciding what to ask and when to ask the user).
- ❑ 3. to leverage the acquired knowledge in the current and future inference process.
- ❑ 4. to perform 1, 2 and 3 in a lifelong manner for continuous knowledge learning.
- We envision that the proposed system is incorporated in a chatbot in a multi-user environment.
 - ❑ The system can perform cross-verification with other users by asking them whether facts) from the particular user is correct.

LiLi: Modeled as Knowledge Base Completion

- We focus on fact triples: e.g., Obama is a citizen of USA
 - *(Obama, CitizenOf, USA)*
- **KB completion (KBC)**: a binary classification problem
 - Given a query triple, (s, r, t) , predict whether the source entity s and target entity t can be linked by the relation r .
 - This problem is solved under the *closed-world* assumption, i.e., s , r and t are all *known* to exist in the KB
- For conversation, we need to remove this **closed-world assumption**

Open-world knowledge base completion (OKBC)

- The new problem *open-world knowledge base completion*:
 - s, r, or t may not be in the KB.
- 1. Mapping open-world to closed-world.
 - By asking the user questions to convert the open-world problem to a closed-world problem.
 - This acquires some new knowledge and will be added to KB
 - The updated with KB (more knowledgeable)
- 2. Solving the problem in the closed-world (C-PR).
 - Prediction – the prediction may not be correct, but not a problem.

System actions

- If the relation r is unknown, ask for a clue. ask the user to provide a clue (+ve example) c^+ .
- If an entity s/t is unknown, ask for connecting link (CLQ). Ask the user to connect unknown entities s and/or t with the KB.
 - System will suggest (the most contextually relevant node/entity)
- Ask missing link query (MLQ). Formulate a missing link query (MLQ) to ask the user
- Enumerate path features (for predictor).
- Invoke Predictor.

An example

User: (Obama, CitizenOf, USA)? “Is Obama a citizen of USA?” [Query]

LiLi: I do not know what “**CitizenOf**” mean? Can you provide me an example? [Ask for Clue]

User: (David Cameron, CitizenOf, UK). “David Cameron is a citizen of UK.” [SF1]

LiLi: Got it. Can you tell me how “**Obama**” and “**Honolulu**” are related? [CLQ]

User: (Obama, BornIn, Honolulu). “Obama was born in Honolulu.” [SF2]

LiLi: Got it. Can you tell also me how “**Honolulu**” and “**Hawaii**” are related? [MLQ]

User: (Honolulu, CapitalOfState, Hawaii). “Honolulu is the state capital of Hawaii.” [SF3]

LiLi: (Obama, CitizenOf, USA) is correct. [Answer]

Experiments

Table 4: Dataset statistics [*kwn* = known, *unk* = unknown]

KB Statistics	Freebase (FB)	WordNet (WN)
# Relations ($\mathcal{K}_{org} / \mathcal{K}_b$)	1,345 / 1,273	18 / 12
# Entities ($\mathcal{K}_{org} / \mathcal{K}_b$)	13, 871 / 13, 223	13, 595 / 13, 150
# Triples ($\mathcal{K}_{org} / \mathcal{K}_b$)	854, 362 / 652, 790	107, 146 / 66, 338
# Test relations (<i>kwn</i> / <i>unk</i>)	25 (17 / 8)	18 (12 / 6)
# Train / valid / test instances	11,260 / 1223 / 7083	6628 / 711 / 3500
Entity statistics in Test Data query triples [<i>s</i> = source entity ; <i>t</i> = target entity]		
Avg. % triples per relation with only <i>s</i> <i>unk</i>	16.28	13.29
Avg. % triples per relation with only <i>t</i> <i>unk</i>	16.29	10.94
Avg. % triples per relation both <i>s</i> and <i>t</i> <i>unk</i>	4.69	4.17

Prediction results

Table 5: Comparison of predictive performance of *various versions* of CKLE [% TTO = % of Test Triples Observed].

% TTO	Models	Freebase									WordNet								
		<i>known Relations</i>			<i>unknown Relations</i>			<i>Overall</i>			<i>known Relations</i>			<i>unknown Relations</i>			<i>Overall</i>		
		P(+)	F(+)	B-Acc	P(+)	F(+)	B-Acc	P(+)	F(+)	B-Acc	P(+)	F(+)	B-Acc	P(+)	F(+)	B-Acc	P(+)	F(+)	B-Acc
UN-FILTERED [evaluation on all test queries, irrespective of whether user can answer any CLQs or MLQs]																			
10%	F-th	0.54	0.40	0.58	0.48	0.22	0.52	0.53	0.34	0.56	0.75	0.35	0.59	0.52	0.58	0.64	0.59	0.47	0.62
	BG	0.48	0.52	0.62	0.42	0.50	0.53	0.46	0.51	0.59	0.64	0.66	0.74	0.44	0.54	0.57	0.54	0.61	0.69
	CKLE	0.51	0.55	0.64	0.45	0.38	0.53	0.49	0.50	0.60	0.63	0.58	0.69	0.61	0.6	0.68	0.62	0.59	0.69
50%	F-th	0.49	0.36	0.56	0.57	0.41	0.59	0.52	0.37	0.57	0.72	0.41	0.61	0.41	0.47	0.57	0.52	0.44	0.60
	BG	0.45	0.48	0.59	0.43	0.55	0.58	0.44	0.51	0.59	0.62	0.64	0.73	0.37	0.51	0.56	0.48	0.58	0.67
	CKLE	0.49	0.52	0.62	0.50	0.52	0.61	0.49	0.52	0.61	0.63	0.62	0.71	0.57	0.54	0.66	0.61	0.59	0.69
100%	F-th	0.50	0.36	0.56	0.53	0.39	0.58	0.51	0.37	0.57	0.73	0.40	0.61	0.39	0.48	0.56	0.49	0.44	0.59
	BG	0.46	0.50	0.60	0.42	0.55	0.60	0.44	0.52	0.60	0.62	0.62	0.71	0.36	0.50	0.55	0.48	0.57	0.65
	CKLE	0.49	0.51	0.62	0.48	0.52	0.61	0.49	0.51	0.62	0.64	0.63	0.72	0.59	0.55	0.66	0.62	0.60	0.70
FILTERED [evaluation on test queries for which user has answered atleast one CLQs or MLQs (when asked)]																			
10%	F-th	0.53	0.49	0.55	0.52	0.32	0.51	0.53	0.43	0.53	1.0	0.24	0.56	0.81	0.85	0.7	0.85	0.52	0.58
	BG	0.58	0.62	0.62	0.56	0.65	0.58	0.57	0.64	0.61	0.86	0.88	0.57	0.90	0.95	0.83	0.88	0.90	0.68
	CKLE	0.56	0.61	0.60	0.5	0.47	0.51	0.54	0.57	0.57	1.0	0.70	0.77	0.8	0.8	0.65	0.90	0.74	0.71
50%	F-th	0.49	0.47	0.54	0.59	0.46	0.52	0.53	0.46	0.53	0.86	0.43	0.34	0.78	0.75	0.64	0.81	0.57	0.48
	BG	0.51	0.58	0.58	0.56	0.68	0.52	0.54	0.57	0.62	0.91	0.92	0.60	0.81	0.86	0.63	0.87	0.90	0.62
	CKLE	0.52	0.58	0.58	0.59	0.6	0.53	0.54	0.59	0.56	0.93	0.78	0.68	0.80	0.76	0.58	0.88	0.77	0.62
100%	F-th	0.52	0.49	0.54	0.54	0.45	0.50	0.52	0.48	0.53	0.88	0.45	0.44	0.83	0.82	0.53	0.85	0.61	0.44
	BG	0.51	0.58	0.56	0.53	0.66	0.51	0.52	0.61	0.55	0.91	0.92	0.59	0.87	0.91	0.66	0.89	0.92	0.62
	CKLE	0.53	0.60	0.58	0.54	0.59	0.51	0.53	0.60	0.56	0.94	0.83	0.66	0.87	0.82	0.66	0.91	0.82	0.64

Outline

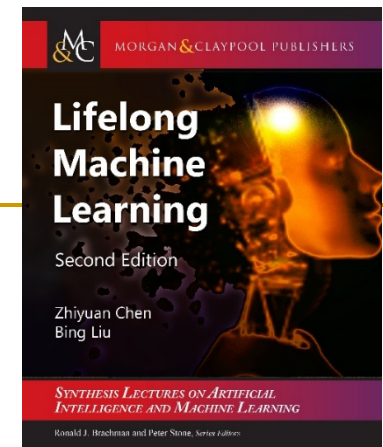
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Summary

- LL wants to enable an AI agent to learn continuously and to make use of knowledge learned in the past to help future learning and problem solving.
- A large space with huge challenges (Chen & Liu, 2016, 2018 book):
 - Correctness and applicability of knowledge, knowledge representation and reasoning, composition, **interactive learning**, etc.
- Learning in conversation interactively is promising.
 - Without it, a chatbot will not be intelligent.
 - Next generation of chatbots should have the self-learning capability.

Thank You

Q&A



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References: <https://www.cs.uic.edu/~liub/lifelong-learning.html>